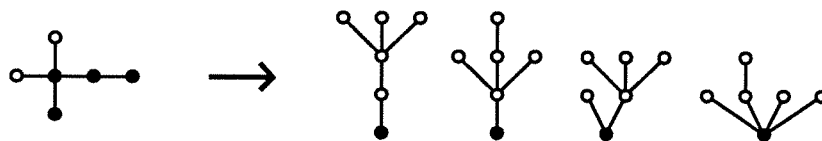


# 4

## Rooted Trees ( $v \leq 10$ ) with probabilities

A rooted tree differs from an ordinary tree by having one vertex identified as the root (●). The root usually represents the beginning of a process or the top of a hierarchical organization. Each vertex stands at some remove from the root, along a unique procedural path or chain of command. The distance of a vertex from the root is its *depth* (or level), and the depth of the tree is the maximum depth of its vertices. Vertices in a rooted tree are related to each other by terms like parent, child, ancestor, descendant, sibling, etc. But genealogically speaking, rooted trees are usually drawn upside down.

One way of generating rooted trees is by choosing vertices in ordinary trees to act as roots. The tree below generates four different rooted trees, and no other ordinary tree will duplicate any of these four. In general, for every symmetry class of the vertex set of the ordinary tree there is one distinct rooted tree.



As a structure that spans the vertices of a connected graph, a tree can represent a search through the graph. There are two main types of search tree — breadth-first and depth-first — and their algorithms are described below in plain language. Each builds a spanning tree within a graph by appending edges to an initially empty set, choosing

new edges that form no cycle with the existing edges. Beyond these similarities, breadth-first has the structure of an outline, while depth-first resembles a drainage system — a river with tributaries — or a spine with ribs.

### Breadth-First Search

- choose a vertex to be the root of the search
  - Level 1: find its neighbors I, II, III, IV, . . . and append them to the root
  - Level 2: find neighbors of I (A, B, C, . . . ) that form no cycle, append to I
  - find neighbors of II (A', B', C', . . . ) that form no cycle, append to II
  - repeat for III, IV, . . .
  - Level 3: find neighbors of A (1, 2, 3, . . . ) that form no cycle, append to A
  - find neighbors of B (1', 2', 3', . . . ) that form no cycle, append to B
  - repeat for C, D, . . .
  - repeat for A', B', C', . . .
  - repeat for A'', B'', C'', . . .
  - . . .
  - Level 4: find neighbors of 1 (a, b, c, . . . ) that form no cycle, append to 1
  - repeat for 2, 3, . . .
  - repeat for 1', 2', 3', . . .
  - . . .
- continue until all vertices are in the tree

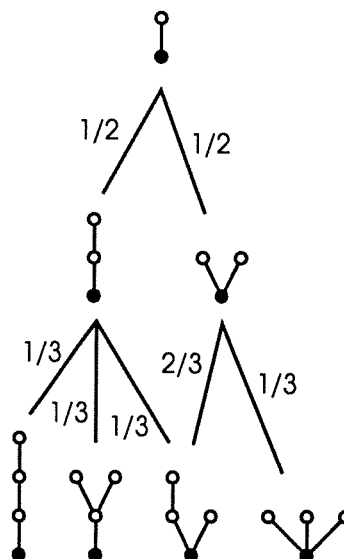
### Depth-First Search

- choose a vertex  $A_0$  to be the root of the search
  - Level 1: connect  $A_0$  to a neighbor  $A_1$
  - Level 2: connect  $A_1$  to a neighbor  $A_2$  that forms no cycle
  - Level 3: connect  $A_2$  to a neighbor  $A_3$  that forms no cycle
  - Level 4 through n: repeat until stuck at  $A_n$ . Path  $A_0$  through  $A_n$  forms the spine.
  - backtrack to  $A_{n-1}$  and connect to another neighbor  $B_n$ , and that to  $B_{n+1}, \dots$  forming no cycles
  - continue depth search out of  $A_{n-1}$ , backtracking if necessary, until stuck
  - backtrack to  $A_{n-2}$ , do depth search to  $C_{n-1}, C_n, \dots$  backtracking if necessary
  - . . .
- continue backtracking along the spine to the root, if necessary, until all vertices are in the tree

Notice that breadth-first is the way an outline is constructed, but the order in which an outline is written and read (I, A, 1, a, (1), . . . ) is depth-first.

The probabilities of randomly built rooted trees are determined in the same way as probabilities of ordinary trees (Ch 3, p 65) — with one simple difference. The process begins with the root. Then, as before, the rest is leaf addition, with every vertex equally likely to be the attachment point.

For  $v = 8$  and 9 the denominator of probabilities is given once per page.



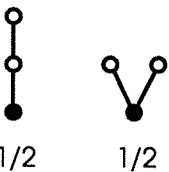
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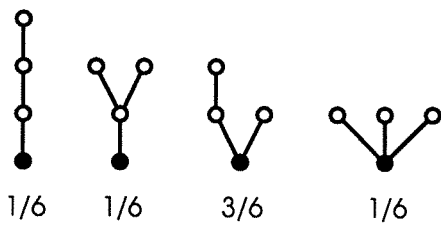
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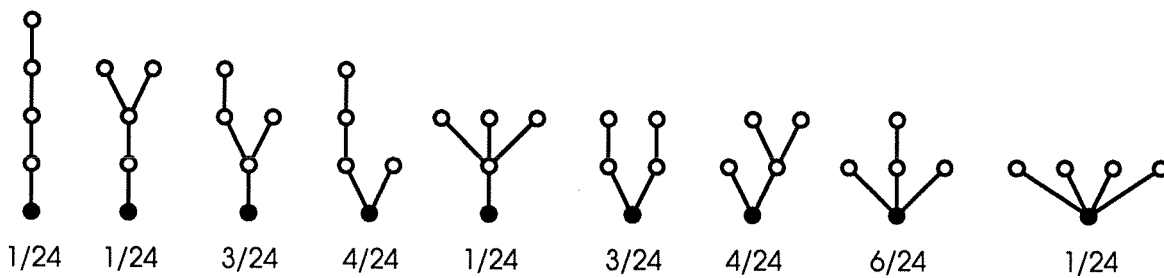
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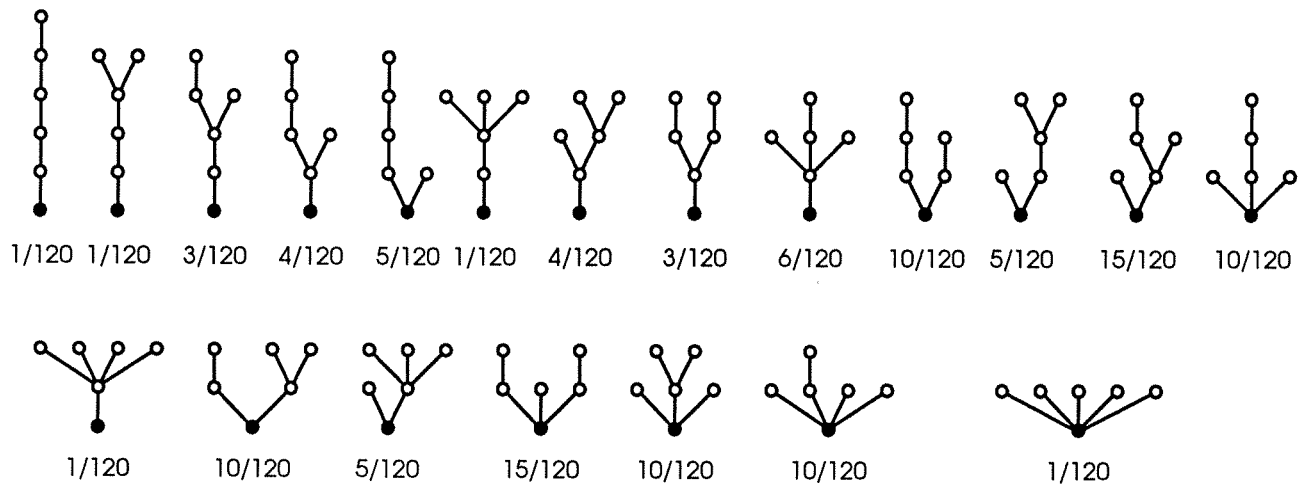
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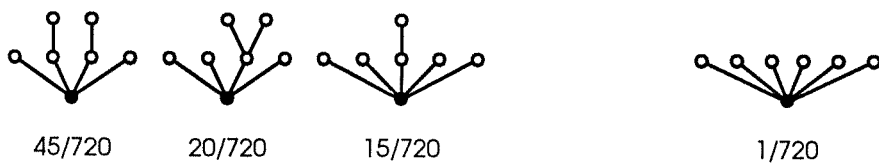
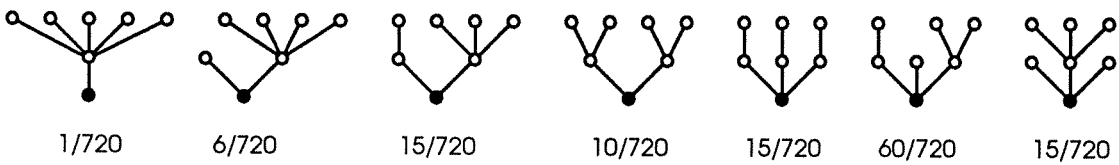
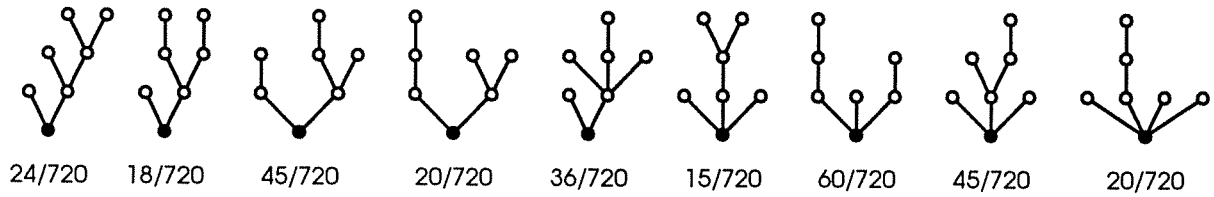
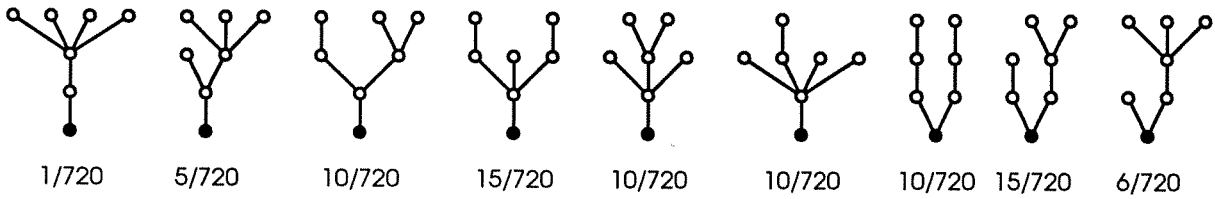
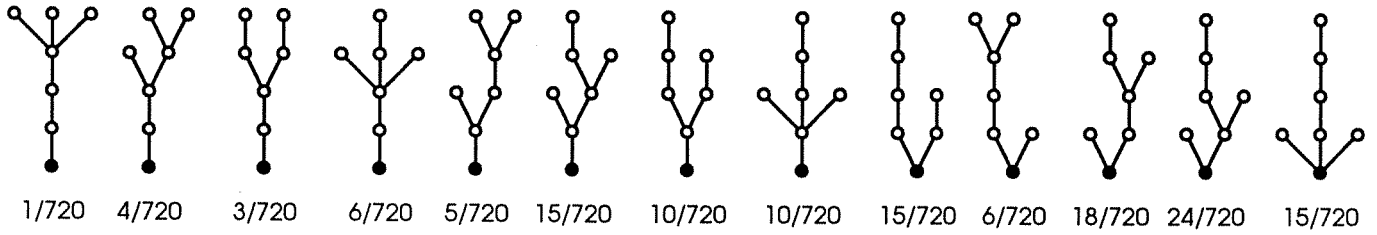
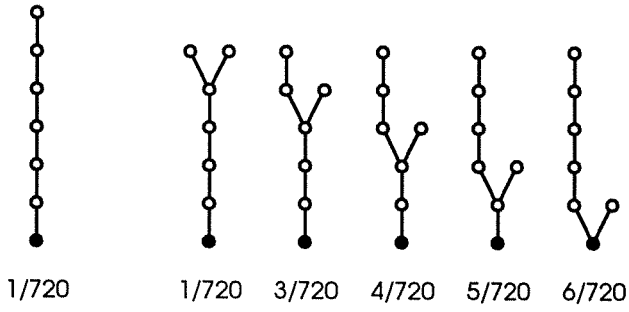
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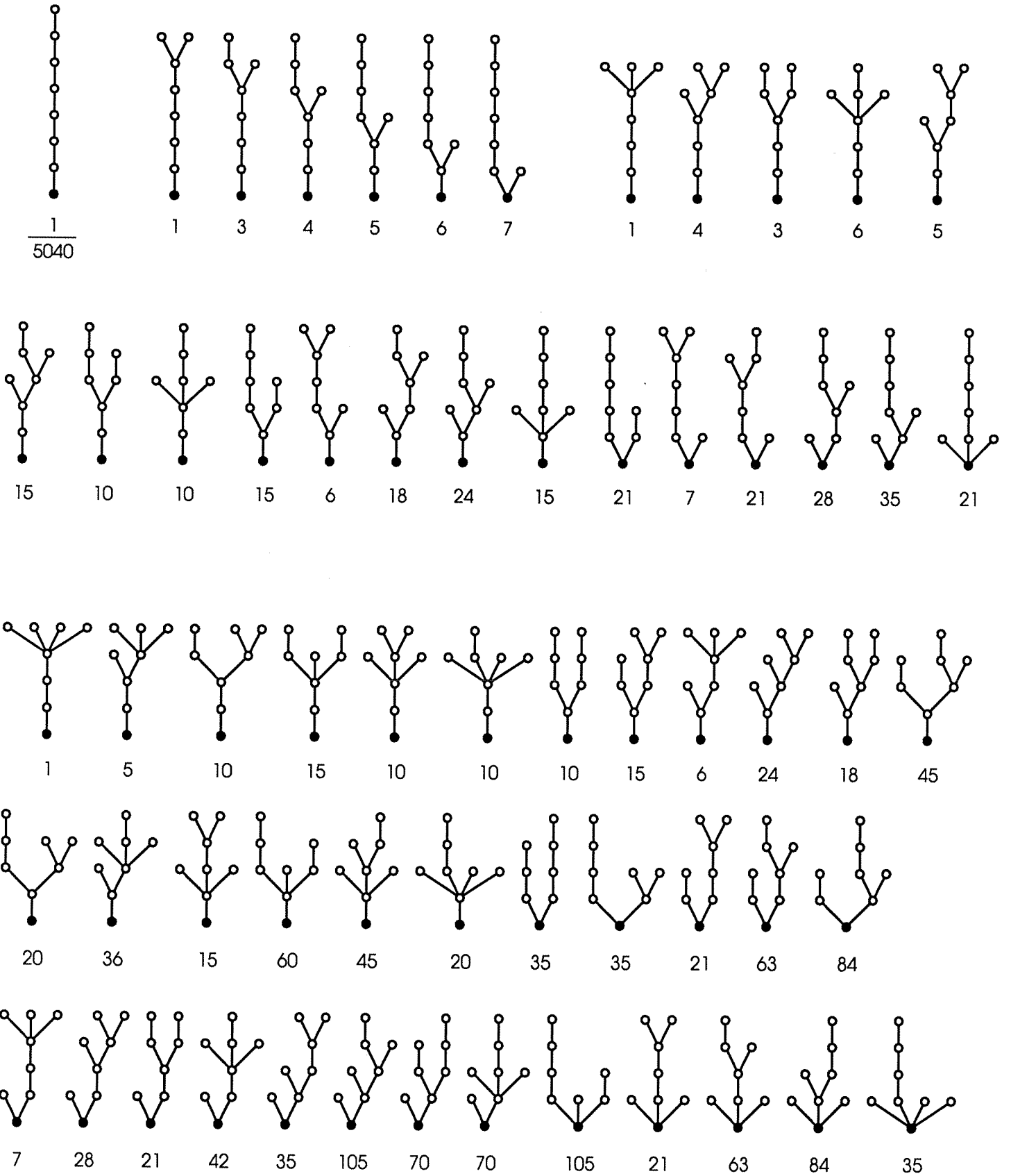
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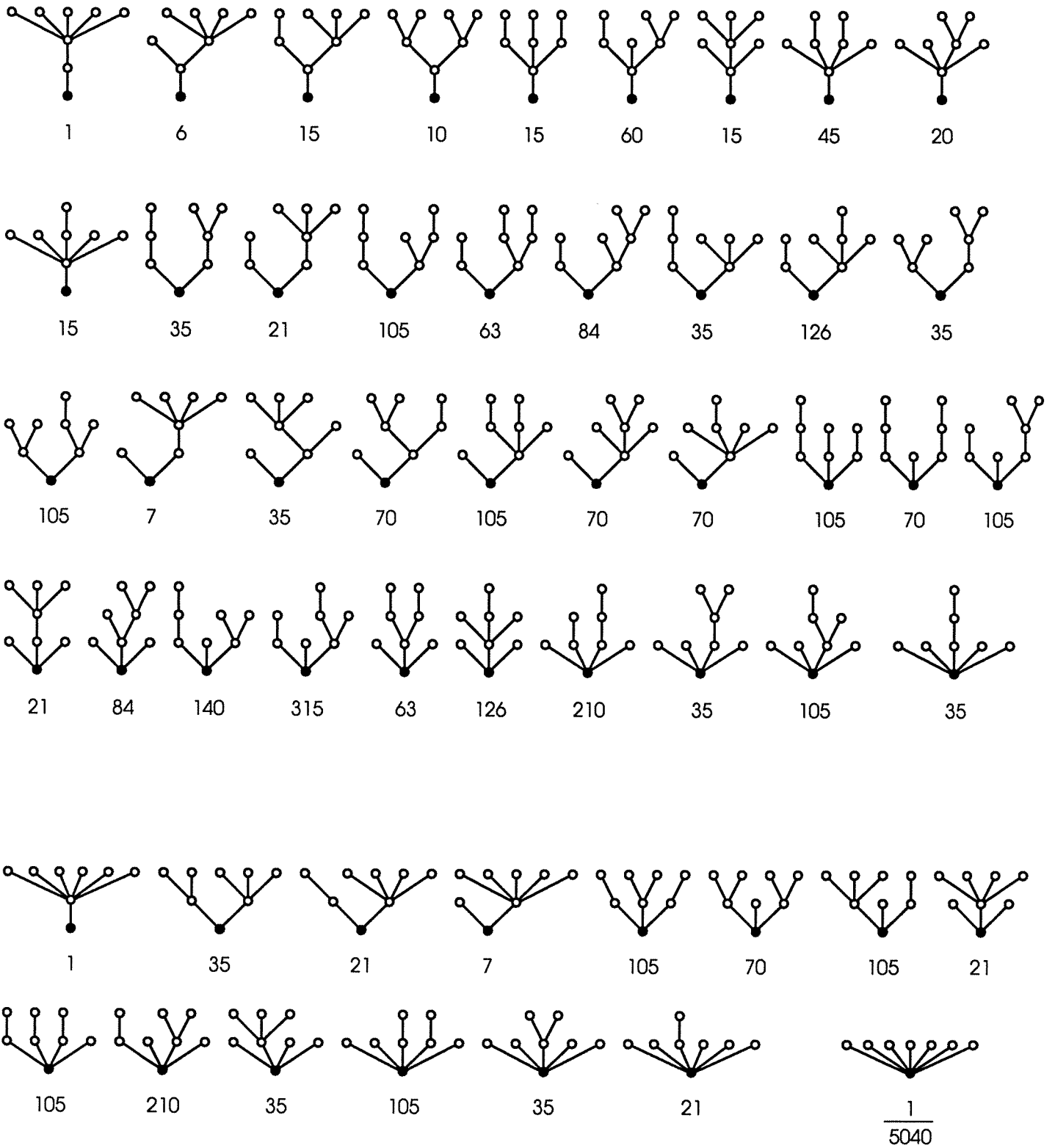
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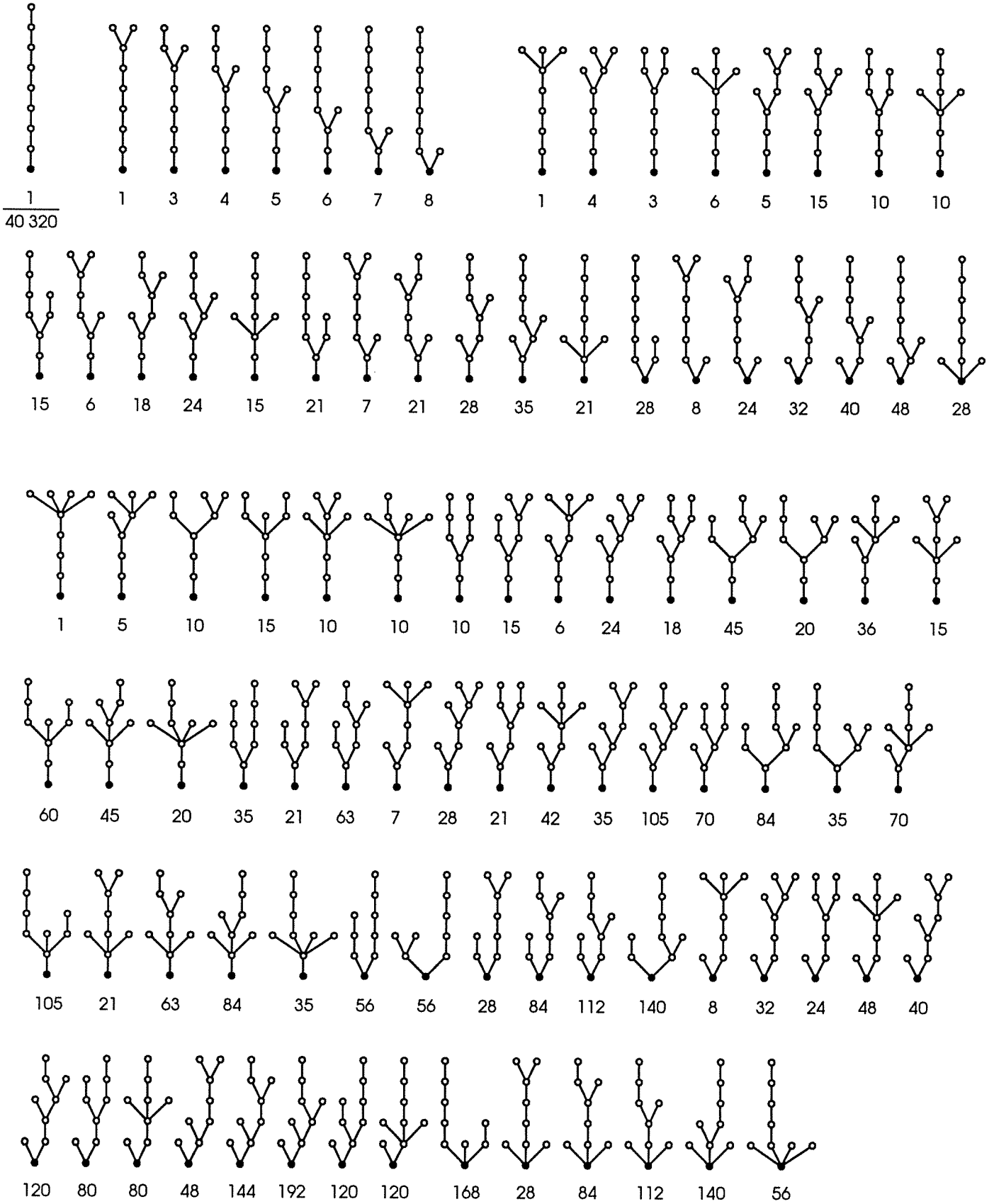
v = 8



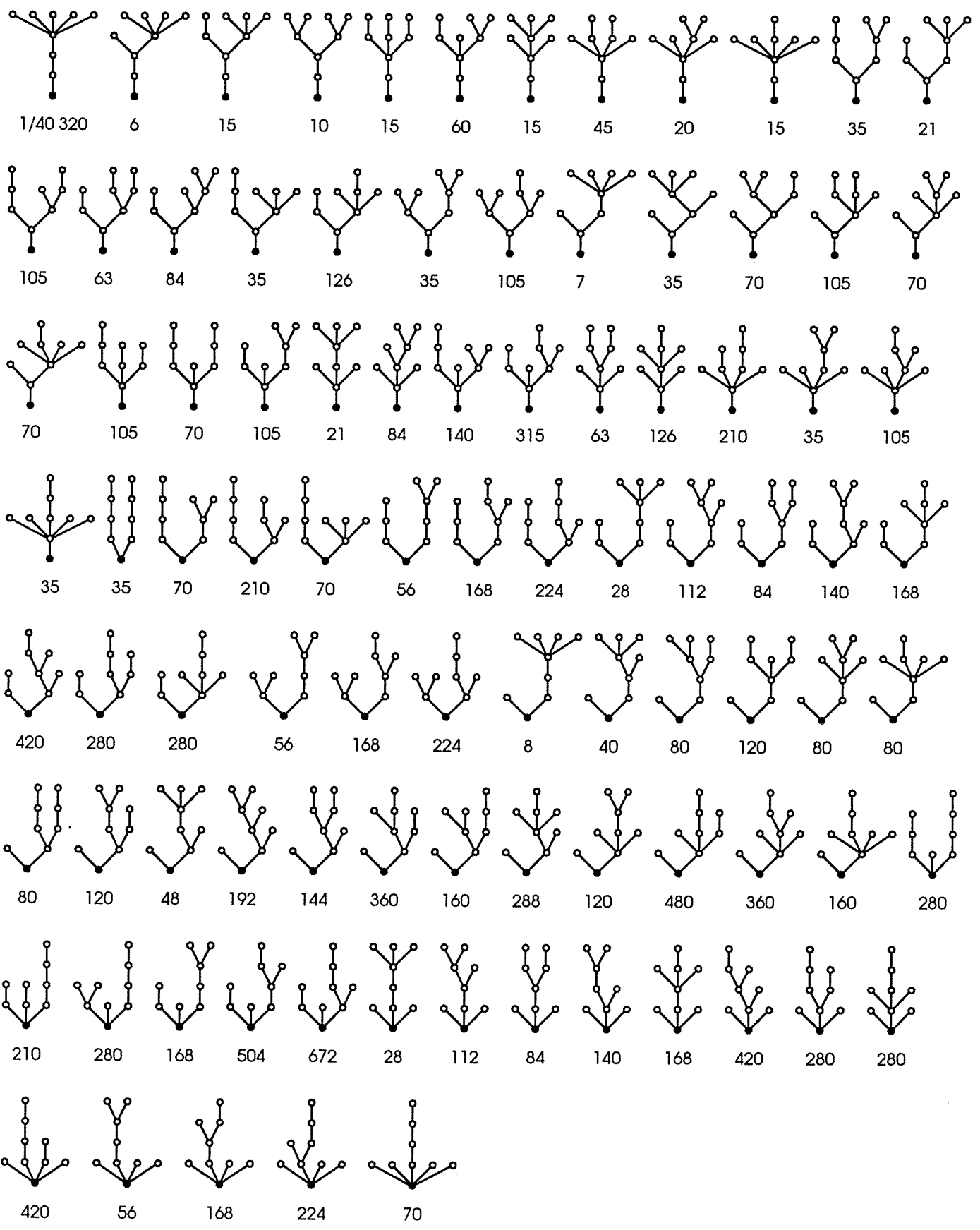
v = 8



$v = 9$

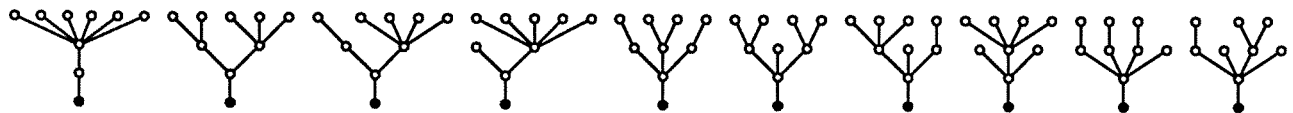


v = 9

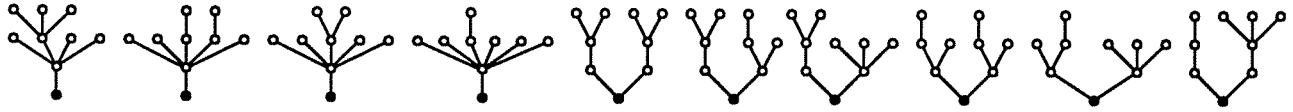




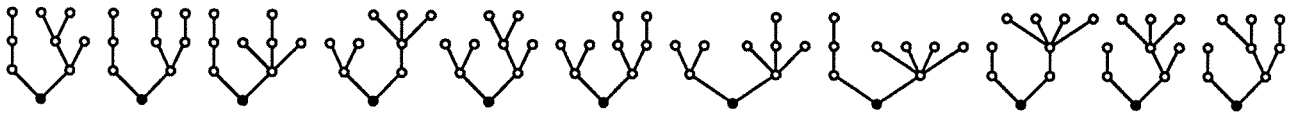
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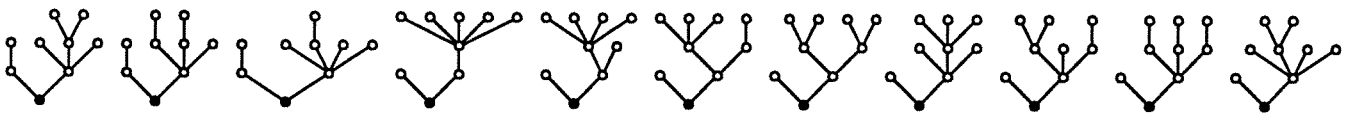
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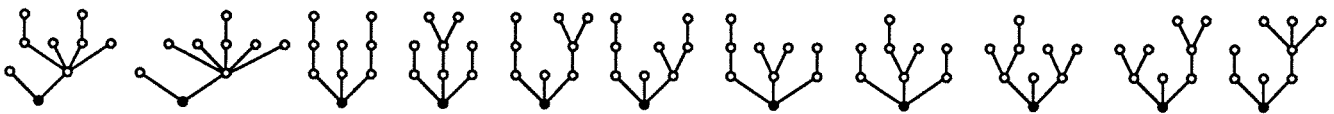
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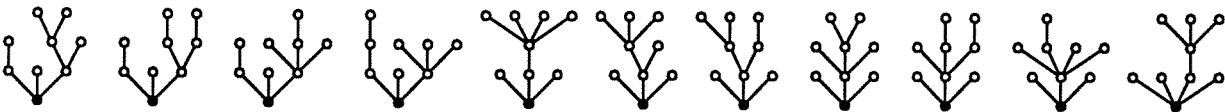
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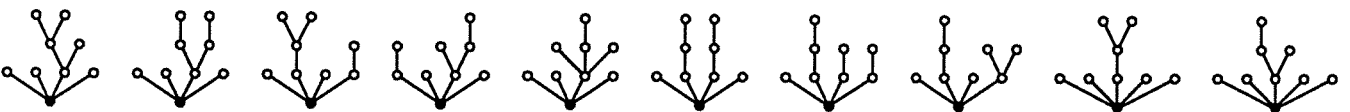
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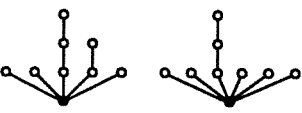
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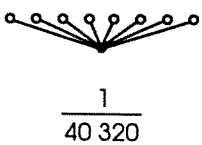
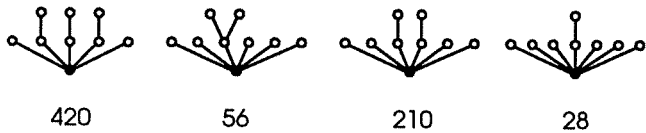
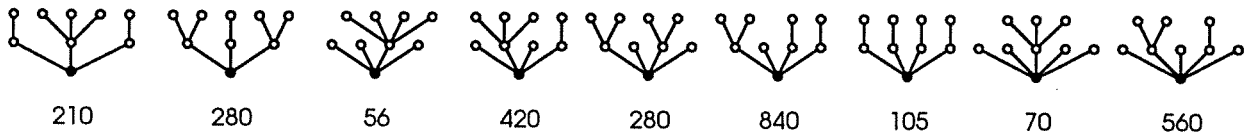
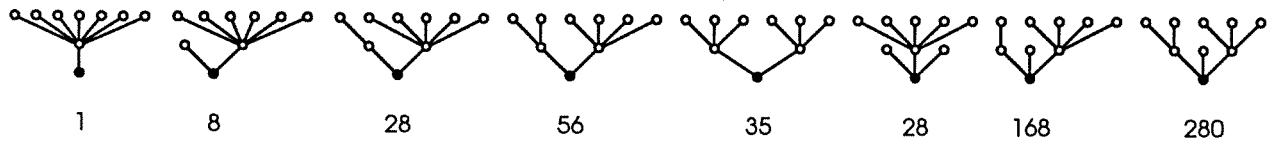
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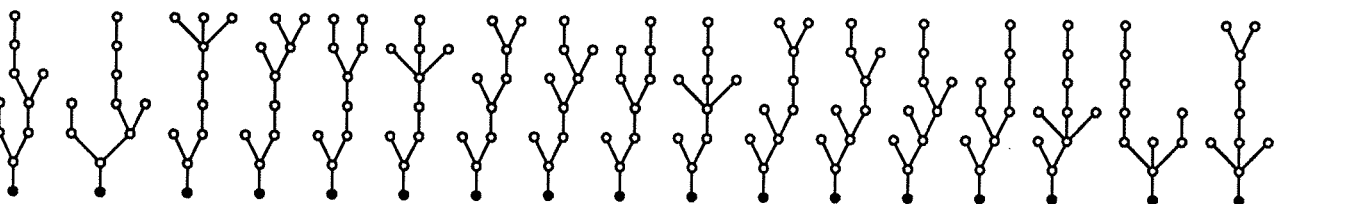
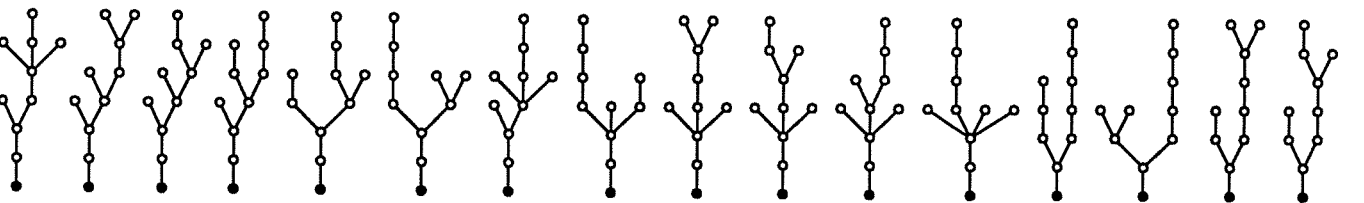
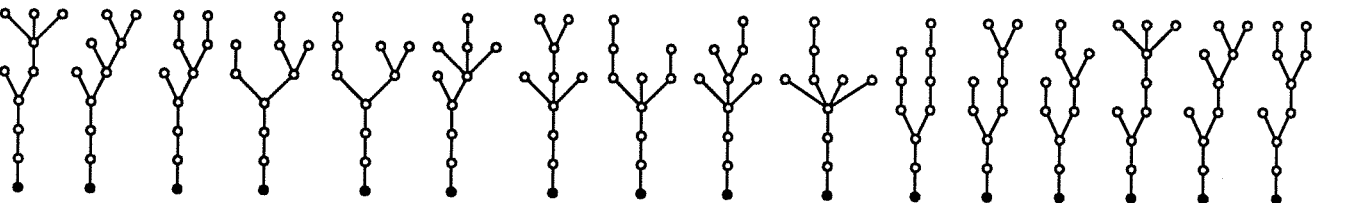
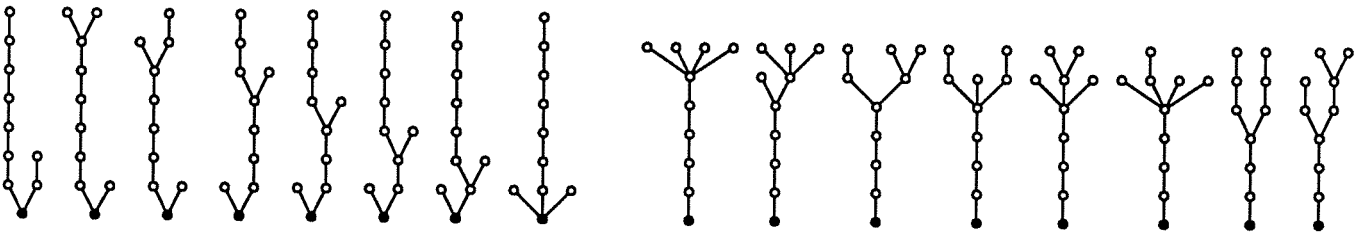
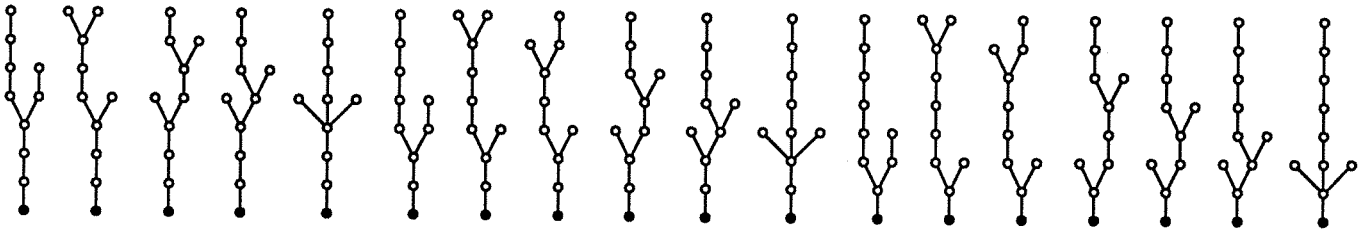
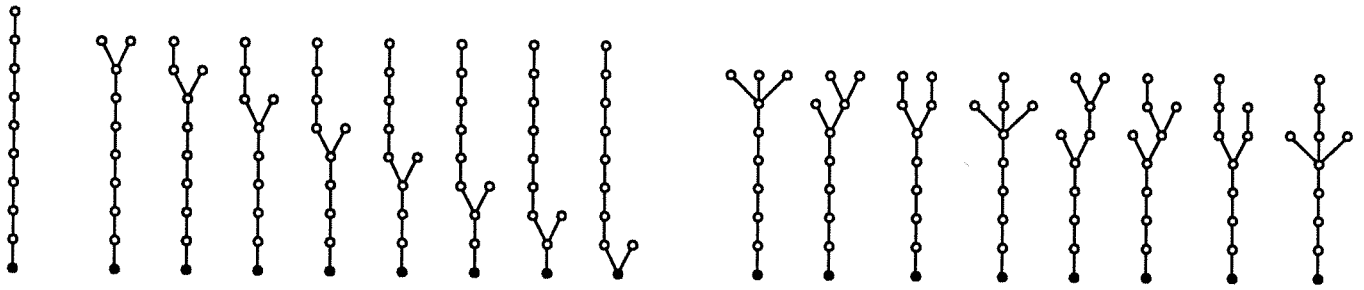
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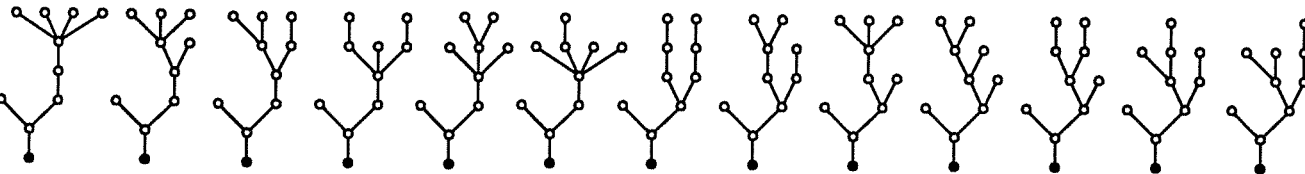
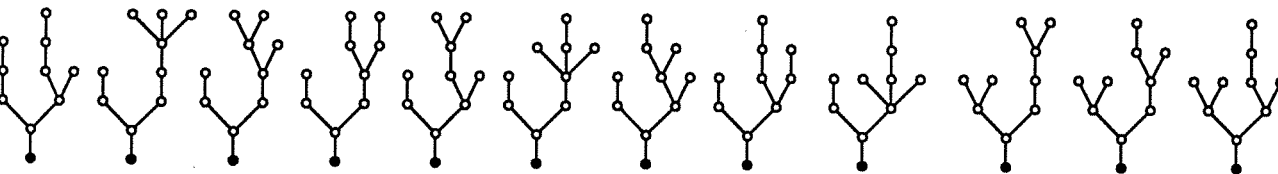
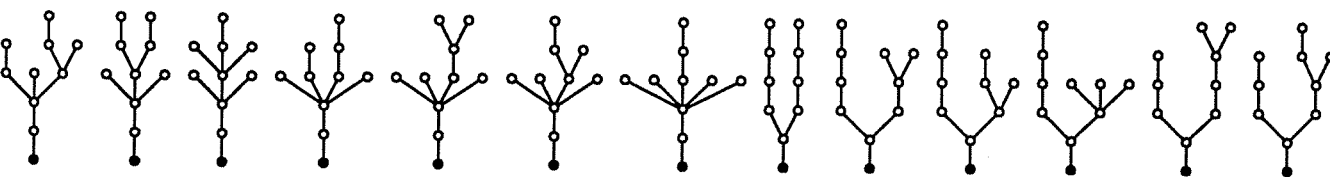
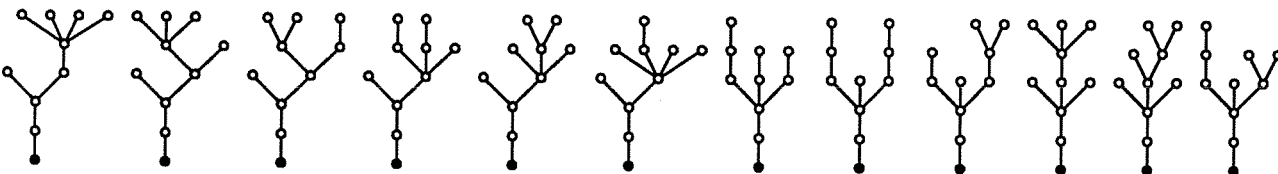
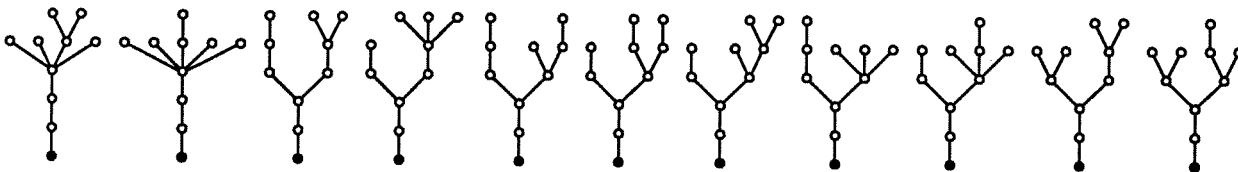
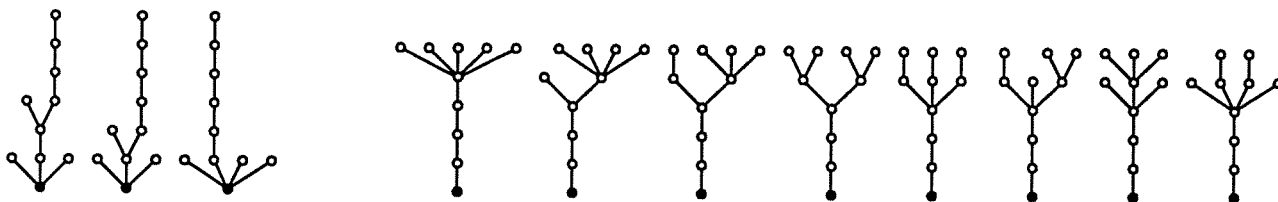
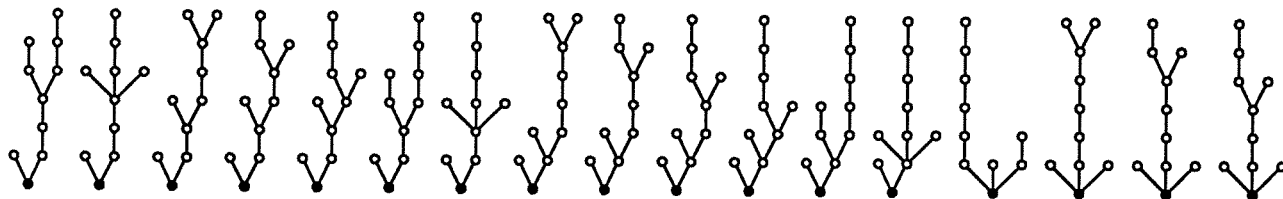
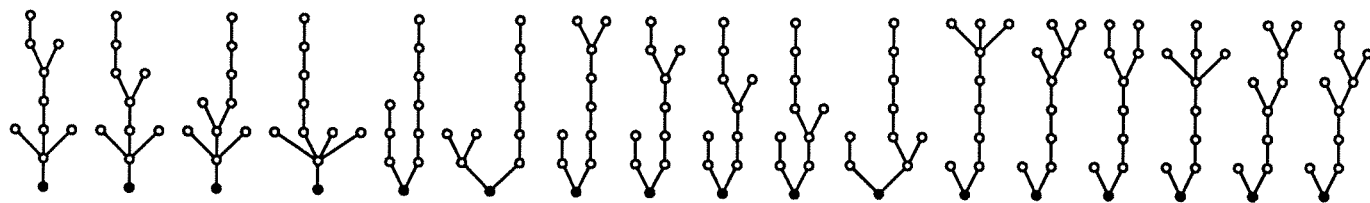


560 56

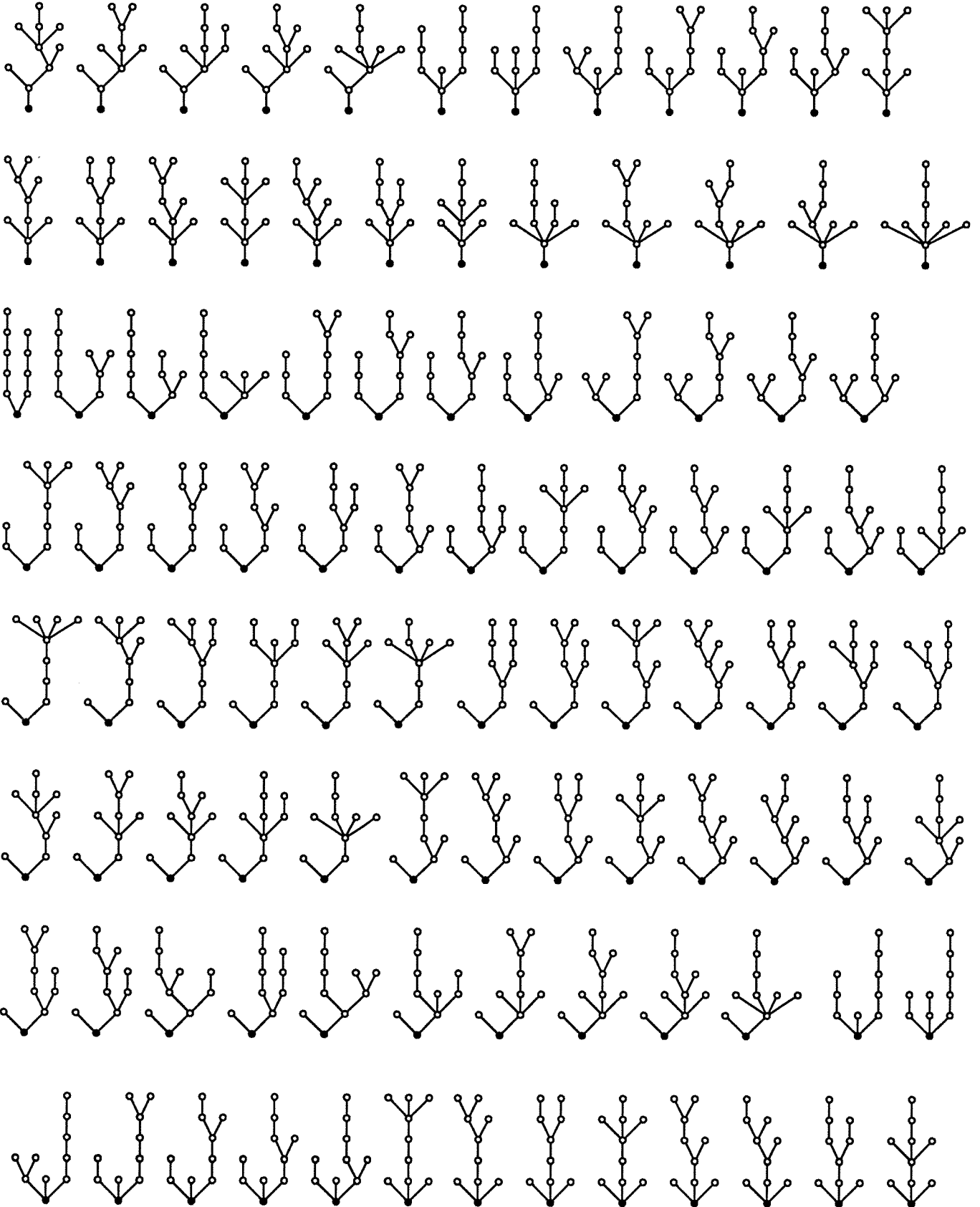


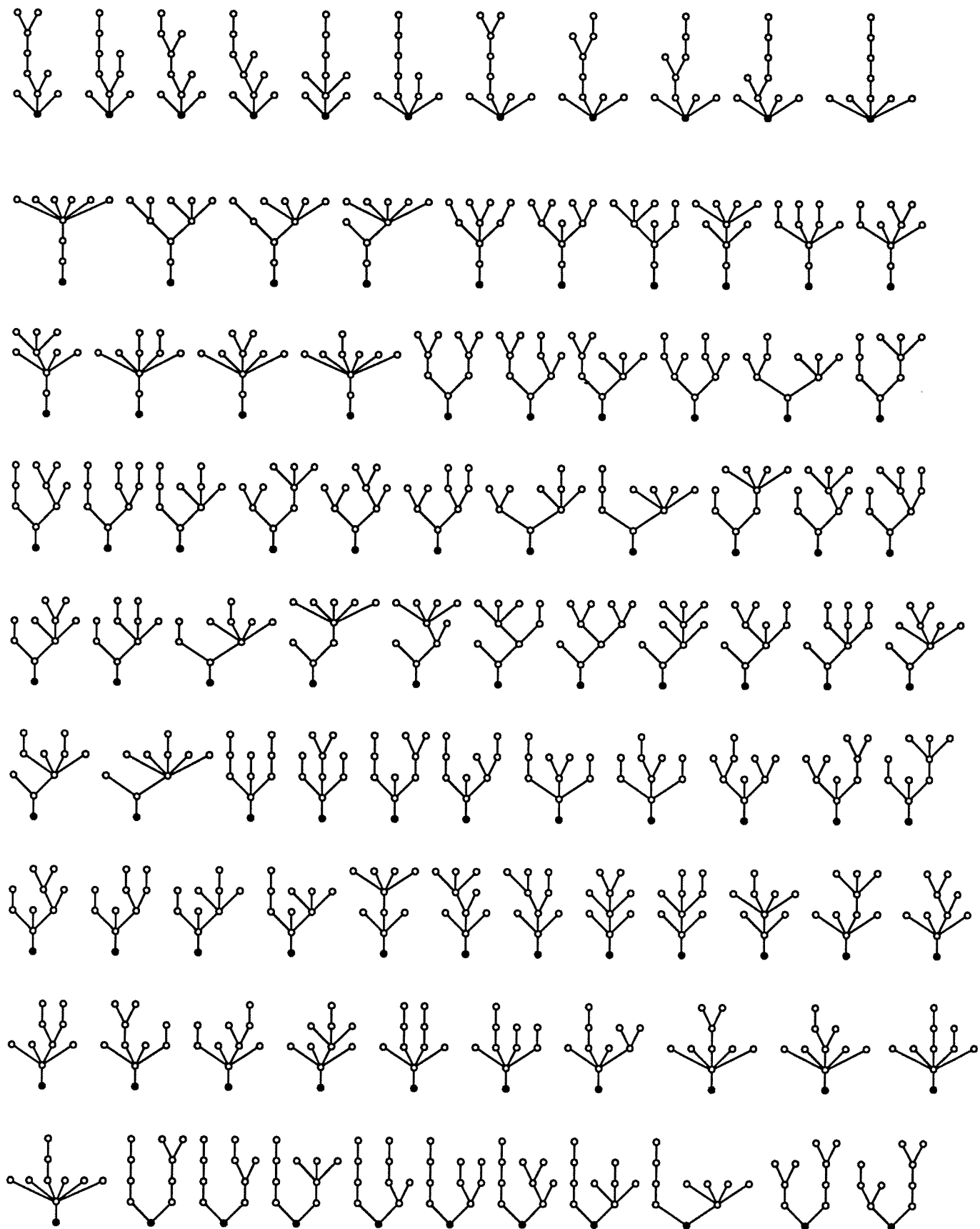
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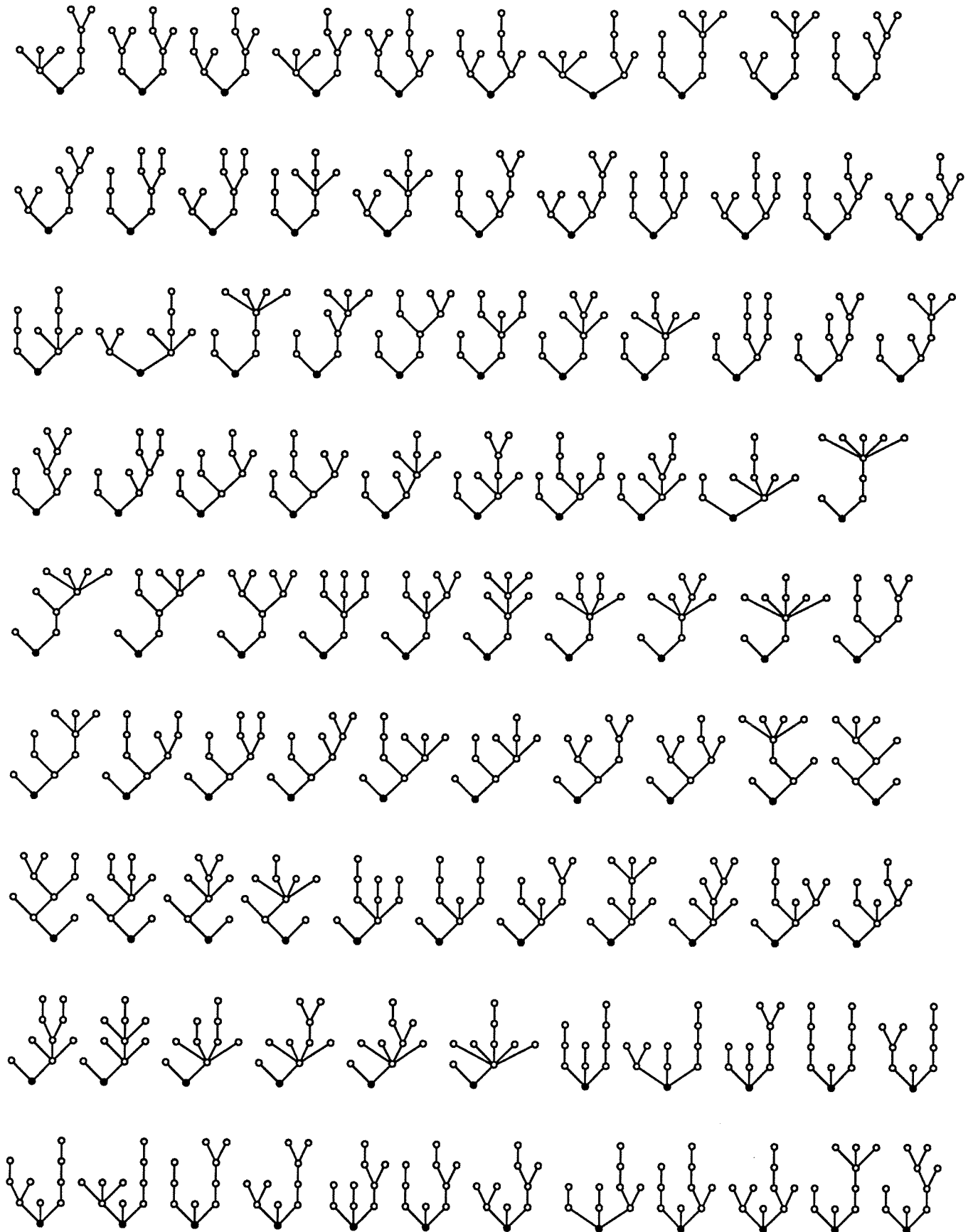


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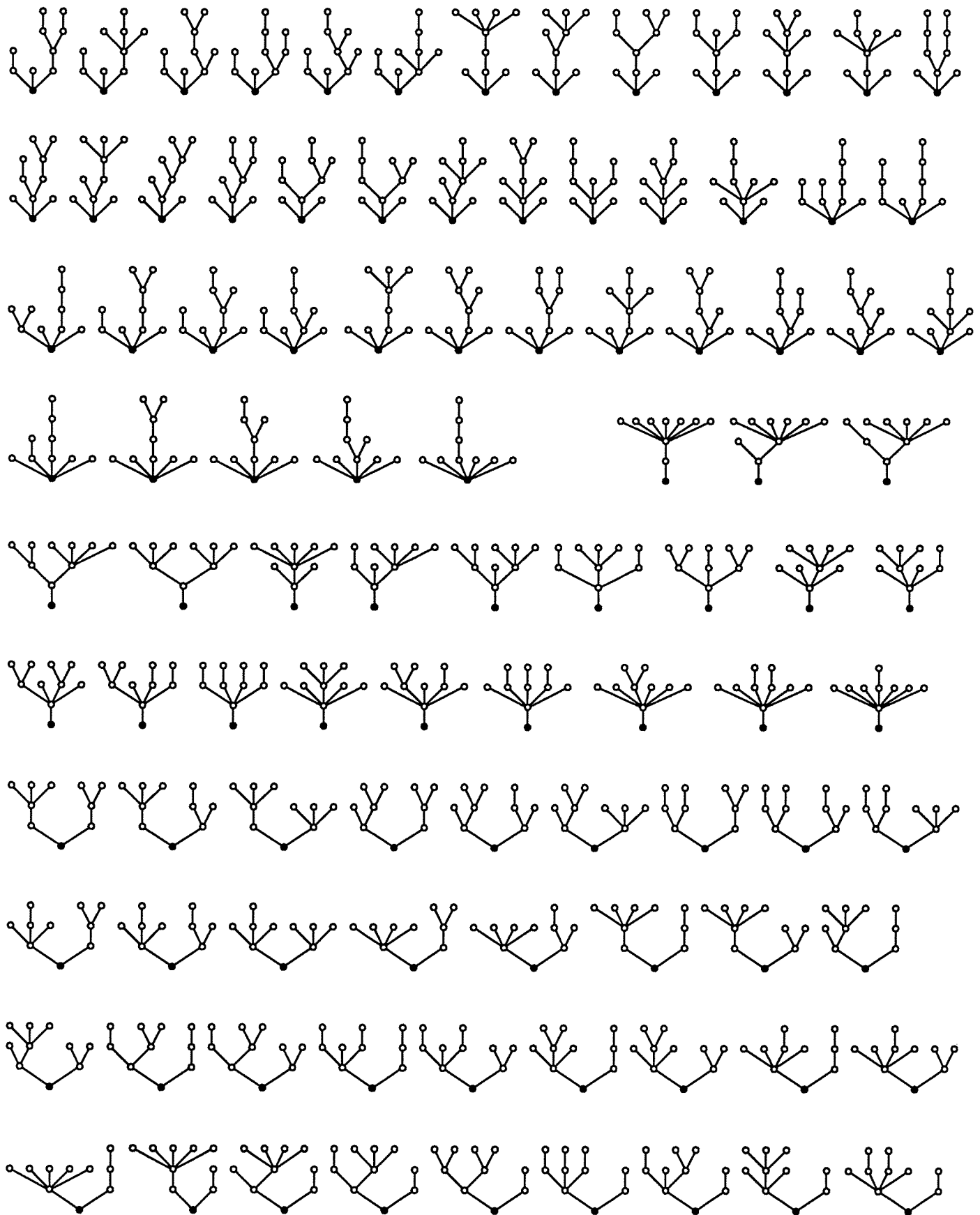




v = 10

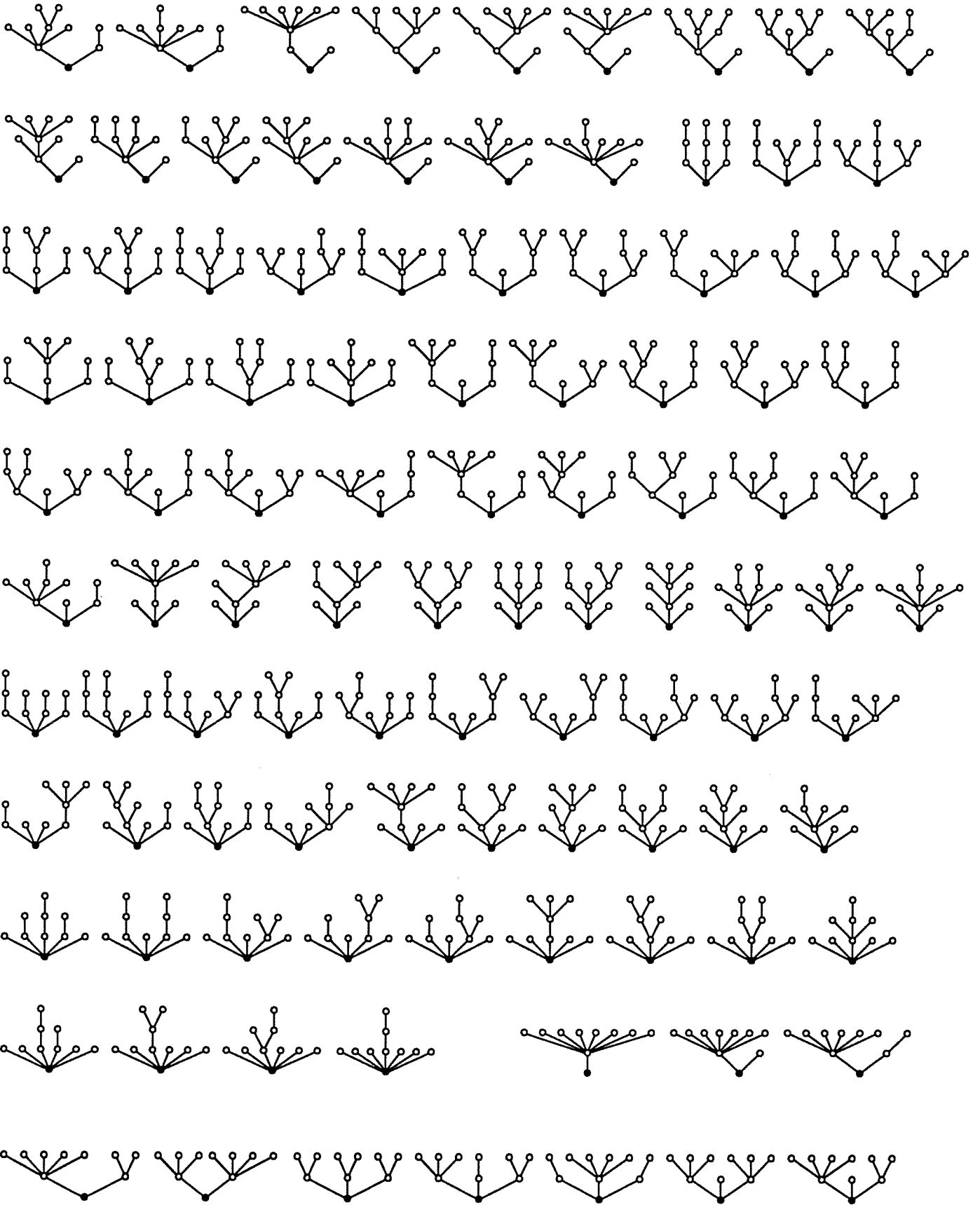


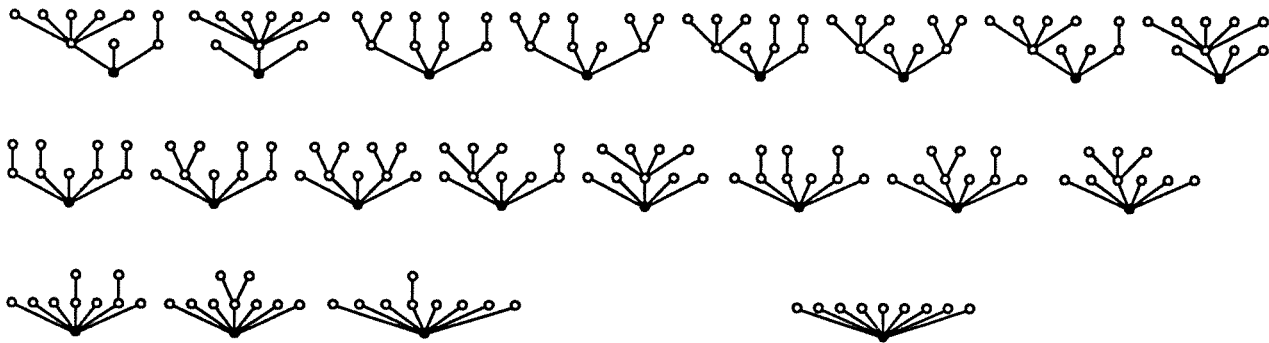
v = 10





$v = 10$





Numbers of rooted trees by depth  $d$  or breadth  $b$

$v$	$d=1$	2	3	4	5	6	7	8	9	10	11	12	totals	mean $d$	random mean $d$
1	0												1	0	0
2	1												1	1	1
3	1	1											2	1.5	1.5
4	1	2	1										4	2	2
5	1	4	3	1									9	2.444	2.375
6	1	6	8	4	1								20	2.9	2.658
7	1	10	18	13	5	1							48	3.292	2.957
8	1	14	38	36	19	6	1						115	3.696	3.203
9	1	21	76	93	61	26	7	1					286	4.059	3.424
10	1	29	147	225	180	94	34	8	1				719	4.416	
11	1	41	277	528	498	308	136	43	9	1			1 842*	4.751	
12	1	55	509	1198	1323	941	487	188	53	10	1		4 766*	5.076	
13	1	76	924	2666	3405	2744	1615	728	251	64	11	1	12 486*	5.385	

\*computed by Allen Schwenk, University of Michigan

$v$	$b=1$	2	3	4	5	6	7	8	9	totals	mean $b$
1	0									1	0
2	1									1	1
3	1	1								2	1.5
4	1	2	1							4	2
5	1	4	3	1						9	2.444
6	1	6	8	4	1					20	2.9
7	1	9	18	14	5	1				48	3.333
8	1	12	35	39	21	6	1			115	3.774
9	1	16	62	97	72	30	7	1		286	4.234
10	1	20	103	212	214	120	40	8	1	719	4.647

The 286 rooted trees on 9 vertices  
partitioned by depth and breadth

**breadth** (number of terminal vertices)

	1	2	3	4	5	6	7	8
1								1
2				1	4	9	7	
3			3	20	32	21		
4		1	16	41	35			
5		3	23	35				
6		5	21					
7		7						
8	1							

The 719 rooted trees on 10 vertices  
partitioned by depth and breadth

**breadth**

	1	2	3	4	5	6	7	8	9
1									1
2					2	7	12	8	
3			1	13	48	57	28		
4			11	64	94	56			
5		2	29	79	70				
6		4	34	56					
7		6	28						
8		8							
9	1								